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$$\vec{D} = \epsilon \vec{E} + \vec{P} \quad P \propto E$$

$$\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$$

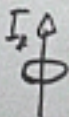
$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$



$$\vec{M} = \chi_m \vec{H} \quad \frac{\vec{M}}{\vec{H}}$$

$$\mu = \mu_0 (1 + \chi_m)$$

$$\vec{M} = \vec{0} \Rightarrow$$



$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I$$

$$B = \frac{\mu_0 I}{2\pi r} \quad H = \frac{I}{2\pi r}$$

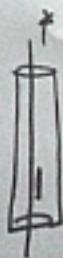


$$H = \frac{I}{2\pi r}$$

$$B = \mu_0 (\vec{H} + \vec{M})$$

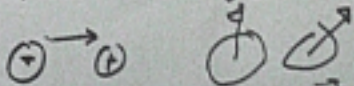
$$\vec{M} = \chi_m \vec{H}$$

$$\vec{B} = \mu_0 (1 + \chi_m) \left(\frac{I}{2\pi r} \right)$$



$$\vec{\nabla} \times \left[\frac{1}{\mu_0} \vec{B} - \vec{M} \right] - \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} = \vec{J}_f$$

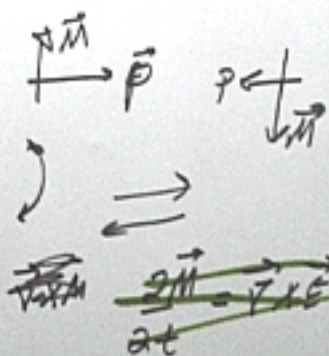
$$\vec{\nabla} \times \vec{H} - \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t} = \vec{J}_f$$

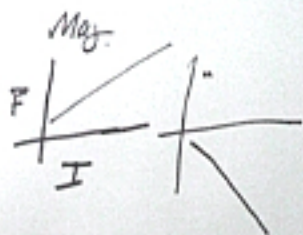


$$\epsilon_0 \frac{\partial \vec{E}}{\partial t} = \vec{J}_p = \frac{\partial \vec{P}}{\partial t}$$

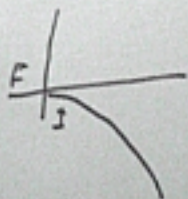
$$\vec{J}_B = \vec{\nabla} \times \vec{M}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_f + \mu_0 \vec{\nabla} \times \vec{M} + \mu_0 \frac{\partial \rho}{\partial t}$$





Nail



$$\vec{\nabla} \times \vec{A} = \vec{B}$$

$$T: [A] \Rightarrow [A] = TM$$

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad -\vec{\nabla} \cdot \vec{V} = \vec{E}$$

$$\vec{\nabla} \times \vec{B} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A})$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A}$$

$$A \rightarrow \vec{A} + \vec{\nabla} \cdot \vec{A}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \cdot \vec{A}) \equiv 0$$

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

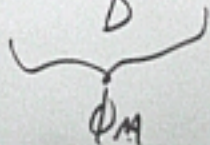
$$\Phi_M = \oint \vec{A} \cdot d\vec{L} = \oint \vec{B} \cdot d\vec{a}$$

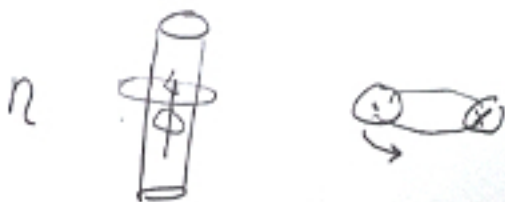
$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

$$\Phi_M = \oint \vec{A} \cdot d\vec{L} = \oint \vec{B} \cdot d\vec{a}$$

$$\oint (\vec{\nabla} \times \vec{A}) \cdot d\vec{a} = \oint \vec{A} \cdot d\vec{L}$$

B


$$\Phi_M$$



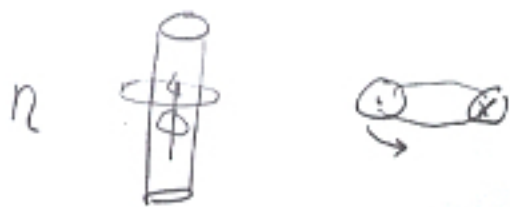
$$\oint \vec{A} \cdot d\vec{L} = A(2\pi r)$$

$$\text{outside } \phi_M = \iint \vec{B} \cdot d\vec{A} = B(\pi a^2)$$

$$\vec{A} = \frac{B_0 r^2}{2s} \hat{\theta}$$

INSIDE: $A(2\pi r) = B \cdot \pi r^2$

$$\vec{A} = \frac{B r}{2} \hat{\theta}$$



$$\oint \vec{A} \cdot d\vec{L} = A(2\pi r)$$

outside $\phi_m = \iint \vec{B} \cdot d\vec{A} = B(\pi a^2)$

$$\vec{A} = \frac{B a^2}{2s} \hat{\phi}$$

INSIDE: $A(2\pi r) = B \cdot \pi r^2$

$$\vec{A} = \frac{B r}{2} \hat{\phi}$$

$$\vec{A} = \frac{B a^2}{2s} \hat{\phi}$$

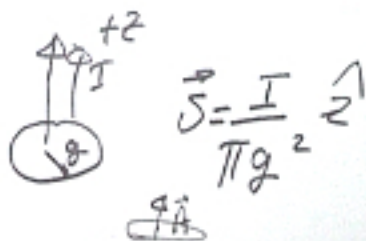
$$\vec{\nabla} \times \vec{A} = \left(\pm \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{x}$$

$$\vec{A} = \frac{B_0^2}{2s} \hat{\phi} \hat{\phi}$$

$$\begin{aligned} \vec{v} \times \vec{A} &= \left(\frac{1}{s} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \hat{s} \\ &+ \left(\frac{\partial A_s}{\partial z} - \frac{\partial A_z}{\partial s} \right) \hat{\phi} \\ &+ \frac{1}{s} \left[\frac{\partial (sA_\phi)}{\partial s} - \frac{\partial A_s}{\partial \phi} \right] \hat{z} \end{aligned}$$

$$\frac{2 \left(s \frac{\partial B_0^2}{\partial s} \right)}{2s} \hat{s} + \frac{2 \left(B_0^2 \right)}{2s} \hat{z}$$

$$\frac{1}{s} \cdot B_0^2 = B_0^2 \hat{z}$$



$$\text{IN: } \oint \vec{B} \cdot d\vec{s} = \mu_0 I (\pi r^2)$$

$$\Rightarrow B = \frac{\mu_0 I}{\pi r^2} \cdot \frac{\pi r^2}{2\pi r}$$

$$\vec{B} = \frac{\mu_0 I r}{2\pi r^2} \hat{\phi}$$

$$\vec{B}_{\text{out}} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$

$$\vec{\nabla} \times \vec{A} = \vec{B}$$

$$B \hat{\phi} \Rightarrow \vec{\nabla} \times \vec{A} = \begin{pmatrix} 2A_3 - \frac{\partial A_2}{\partial z} \\ \frac{\partial A_3}{\partial z} - 2A_1 \end{pmatrix} \hat{\phi}$$

Inside

$$-\frac{\partial A_3}{\partial z} = \frac{\mu_0 I S}{2\pi r^2} \hat{\phi}$$

$$\frac{dA_3}{dz} = -\frac{\mu_0 I S}{2}$$

$$\Rightarrow A_3 = -\frac{\mu_0 I S z^2}{4} + \text{const}$$

$$\vec{A} = -\frac{\mu_0 I S z^2}{4} \hat{\phi} + \underline{\underline{\vec{\nabla} f(x, y, z)}}$$

$$\vec{A} = -\frac{\mu_0 J s^2}{4}$$

$$\vec{\nabla} \times \vec{A} = -\frac{2A_z}{2s} \hat{\phi}$$

$$= -\frac{\mu_0 J}{2} s \hat{\phi}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{\phi} \rightarrow \vec{A}_{out} = \frac{B a^2}{s}$$

$$\vec{\nabla} \times \vec{A} = \vec{B} = \frac{2(sV\phi)}{2s} \cdot \frac{1}{s} \hat{z}$$

$$\vec{\nabla} \times \vec{A} = \hat{\phi} \frac{2A_z}{2s} \Rightarrow \boxed{\frac{2A_z}{2s}}$$

$$= -\frac{2A_z}{2s} = \frac{\mu_0 I}{2\pi s}$$

$$A_z = -\frac{\mu_0 I}{2\pi} \int_s^s ds$$

$$\vec{\nabla} \times \vec{A} = \vec{B}$$

$$\vec{A} = -\frac{\mu_0 \vec{J} s^2}{4}$$

$$\vec{\nabla} \times \vec{A} = -\frac{2A_z}{2s} \hat{\phi}$$

$$= -\frac{\mu_0 \vec{J} s}{2} \hat{\phi}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{\phi} \rightarrow \vec{A}_{out} = \frac{B a^2}{s}$$

$$\vec{\nabla} \times \vec{A} = \vec{B} = \frac{(2(sV\phi))}{2s} \cdot \frac{1}{s} \hat{z}$$

$$\vec{\nabla} \times \vec{A} = \hat{\phi} \frac{2As}{2s} \rightarrow \boxed{\frac{2VAz}{2s}}$$

$$-\frac{dA_z}{ds} = -\frac{\partial A_z}{\partial s} = \frac{\mu_0 I}{2\pi s}$$

$$A_z = -\frac{\mu_0 I}{2\pi} \int \frac{ds}{s}$$

$$= -\frac{\mu_0 I}{2\pi} \left[(-\ln(y)) + \ln(s) \right]$$

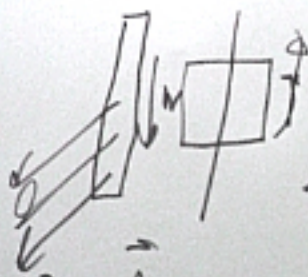
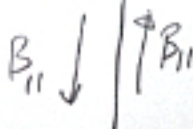
$$\vec{A} = -\frac{\mu_0 I}{2\pi} \ln(s) \vec{z}$$

$$\vec{\nabla} \times \vec{A} = \vec{B}$$

$$\vec{\nabla} \times \vec{A} = -\mu_0 \vec{J}$$

$$\vec{J} = J_0 \hat{z}$$

$$\vec{\nabla}^2 A_z = -J_0 \quad \Delta B_{11} = \mu_0 J$$



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_C$$

$$I_C = J \cdot w$$

$$\vec{A}_{ABSOV} = \vec{A}_{Belo} \quad B(2\pi r) = \mu_0 J w$$

$$= -\mu_0 \frac{J}{2} \quad B = \frac{\mu_0 J}{2}$$