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Time Start \_\_\_\_\_ Time finish \_\_\_\_\_ Pledged \_\_\_\_\_

**Instructions: You have a total of 55 minutes to complete this test.**

**Answer each of the following questions completely.**

**Supply all details that led to your answer and correct SI units where required.**

**Do not discuss any aspect of this test with anyone until I return the test.**

**[1]** A point mass is attached to the end of a massless bar of length  $R$ . The other end of the bar is attached to a hinge at the origin. The mass is observed to have an time-dependence to its angular velocity which is given by  $\theta = \theta_0 + \frac{1}{2}bt^2$  .

**[a]** What is the function that describes the behavior of  $\omega(t)$ ?

**[b]** What is the function that describes the angular acceleration of the mass,  $\alpha(t)$ ?

For the rest of the problem, assume that  $\theta_0 = 0$  ,  $\omega_0 = 0$  ,  $b = 0.4 \frac{\text{rad}}{\text{s}^2}$  and  $R = 0.5 \text{ m}$  .

Answer the following **providing correct SI units**.

**[c]** What is the tangential velocity at  $t = 2 \text{ s}$ ?

**[d]** What is the centripetal acceleration at  $t = 2 \text{ s}$ ?

**[e]** What is the tangential acceleration at  $t = 2 \text{ s}$ ?

**[f]** What is the magnitude of the total acceleration at  $t = 2 \text{ s}$ ?



**[2]** A mass  $m$  is resting on an inclined plane (inclined at an angle  $\theta$ ) at a height  $h$  above a table. The inclined plane is frictionless. In answering this question, you **must use energy considerations**.

**[a]** How fast is the mass moving at the bottom of the plane in terms of  $h$  and  $g$ ?

After the mass is at the bottom of the plane, it slides along the table where the coefficient of friction is  $\mu$ .

**[b]** Draw a correct free body diagram for this system (when the mass is sliding on the table).

**[c]** How far will the mass slide until it stops in terms of  $h$  and  $\mu$ ?

**[d]** If the mass was placed on a compressed spring of spring constant  $k$  which was compressed through a distance  $x$ , how large would  $x$  need to be so that the mass would move through the distance  $z$  if, after the mass left the spring, the coefficient of friction was  $\mu$ . Assume no friction exists until the mass leaves the spring. Express your answer in terms of  $m, g, h$  and  $k$ .

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**[3]** An object of constant mass  $m$  is observed to change its velocity so that  $\Delta \vec{v} = bt \hat{x}$  where  $b$  is a positive constant with SI units of  $\text{m/s}^2$ .

**[a]** Find the functional dependence of the change in **vector** momentum,  $\Delta \vec{P}$ . Express your answer in terms of  $m, b$  and  $t$  with appropriate vector notation.

**[b]** Find the functional dependence of the **vector** impulse that was required. Express your answer in terms of  $m, b$  and  $t$  with appropriate vector notation.

**[c]** Find the functional dependence of the **vector** force that was required assuming that the force started at  $t=0$ . Express your answer in terms of  $m$ , and  $b$  with appropriate vector notation.

**[d]** Suppose that after a time  $t$ , the impulse was removed and the object collided with and compressed a spring of spring constant  $k$  through a distance  $x$ . How much did the spring compress? You may assume that before the impulse was applied, the object was at rest. Express your answer in terms of  $m, b, t$ , and  $k$ .

**[e]** Provide a numerical result for your answer in **[d]** for the case that  $m=8 \text{ kg}$ ,  $k=2 \text{ N/m}$ ,  $b=0.3 \text{ m/s}^2$  and  $t=0.4 \text{ s}$  together with correct SI units.

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**[4]** A point mass  $m_1$  is moving with a speed  $v_{1,B}$ . The other point mass is  $m_2=3m_1$  which is initially at rest. In answering the following questions, your answers are numeric only without units.

**[a]** If the two objects stick together and move off, what is the value of  $\frac{V_{final}}{V_{1,B}}$  ?

**[b]** What is the value of  $\frac{K_{after}}{K_{before}}$  ?

**[c]** Suppose that the collision is completely elastic. What is the value of  $\frac{V_{1,A}}{V_{1,B}}$  ?

**[d]** Again, assuming the collision is completely elastic, what is the value of  $\frac{V_{2,A}}{V_{1,B}}$  ?