

Physics 210	Unquiz 05	Name _____
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A particle of mass m at one instant in time is traveling with a velocity $\vec{v} = 0\hat{x} + v_t\hat{y}$ and is located at $\vec{r} = R\hat{x} + 0\hat{y}$ and is attached to a massless bar hinged at $x=0$, which you may assume here to be the pivot and axis.

(a) Determine the angular momentum vector $\vec{L}$.

(b) Suppose a torque $\vec{\Gamma} = -\tau\hat{z}$ was applied for a time t . What is the final angular momentum?

(c) If the final angular momentum was given by $\vec{L}_f = -mv_t R\hat{z}$, what is the angular impulse required? **Note:** I'll use this symbol to represent angular impulse: $\oint \vec{J} = \vec{\Gamma} \Delta t$ if $\vec{\Gamma} = \overline{\text{constant}}$. There is no commonly used symbol to denote angular impulse and various choices I have seen are H and K , neither of which I find acceptable. Angular impulse is not the most used topic in physics.

(d) Suppose that the torque that produced this angular impulse was supplied for $t=1$ s. How large was the required torque if $m=1$ kg, $v_t=1$ m/s, and $R=1$ m.

(e) Draw a sequence of pictures showing this situation for .

(e-a) Show x, y, z, v_t, R, L_i

(e-c) Show $x, y, z, v_t, R, L_i, F, \Gamma, \Delta L, v_t$ final

A particle of mass m at one instant in time is traveling with a velocity $\vec{v} = 0\hat{x} + v_t\hat{y}$ and is located at $\vec{r} = R\hat{x} + 0\hat{y}$.

(a) Determine the angular momentum vector $\vec{L}$.

$$\vec{L} = \vec{r} \times \vec{p} = mv_t R (\hat{x} \times \hat{y}) = mv_t R \hat{z}$$

(b) Suppose a torque $\vec{\Gamma} = -\tau\hat{z}$ was applied for a time t . What is the final angular momentum?

$$\vec{F} = m\vec{a} = \frac{\Delta\vec{p}}{\Delta t}; \vec{\Gamma} = \vec{R} \times \vec{F} = \vec{R} \times \frac{\Delta\vec{p}}{\Delta t} = \frac{\Delta[\vec{R} \times \vec{p}]}{\Delta t} = \frac{\Delta\vec{L}}{\Delta t} \text{ if } \vec{R} = \text{constant}; \text{ so}$$

$$\vec{\Gamma} = \frac{\Delta\vec{L}}{\Delta t} \Rightarrow \vec{\Gamma} \Delta t = \Delta\vec{L} \Rightarrow -\tau t \hat{z} = \vec{L}_f - \vec{L}_i \Rightarrow \vec{L}_f = \vec{L}_i - \tau t \hat{z} = (mv_t R - \tau t) \hat{z}$$

(c) If the final angular momentum was given by $\vec{L}_f = -mv_t R \hat{z}$, what is the angular impulse required? **Note:** I'll use this symbol to represent angular impulse: $\vec{J} = \vec{\Gamma} \Delta t$ if $\vec{\Gamma} = \text{constant}$. There is no commonly used symbol to denote angular impulse and various choices I have seen are H and K , neither of which I find acceptable. Angular impulse is not the most used topic in physics.

$$\vec{J} = \Delta\vec{L} = \vec{L}_f - \vec{L}_i = -mv_t R \hat{z} - mv_t R \hat{z} = -2mv_t R \hat{z}$$

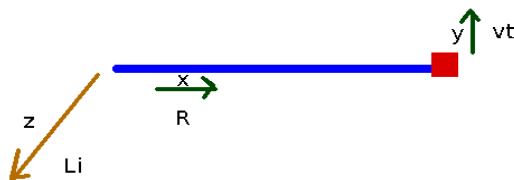
(d) Suppose that the torque that produced this angular impulse was supplied for $t=1$ s. How large was the required torque if $m=1$ kg, $v_t=1$ m/s, and $R=1$ m.

$$\vec{J} = \vec{\Gamma} \Delta t \Rightarrow \vec{\Gamma} = \frac{\vec{J}}{\Delta t} = \frac{\Delta\vec{L}}{\Delta t} = \frac{-2mv_t R \hat{z}}{1\text{ s}} = \frac{-2\text{ kg} \frac{\text{m}^2}{\text{s}}}{1\text{ s}} \hat{z} = -2\text{ kg} \frac{\text{m}^2}{\text{s}^2} \hat{z}$$

$$\text{note } [J_\phi] = \text{Nms} = (\text{energy} \times \text{time}) = \text{kg} \frac{\text{m}^2}{\text{s}}$$

(e) Draw a sequence of pictures showing this situation for .

(e-a) Show x, y, z, v_t, R, L_i



(e-c) Show $x, y, z, v_t, R, L_i, F, \Gamma, \Delta L, v_t \text{ final}$

